

# Yue Meng

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## FIELD OF INTERESTS

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Safety-assured autonomy; Machine learning; Efficient video understanding; 3D reconstruction

## EDUCATION

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**Ph.D. in Aeronautics and Astronautics** Sep. 2020 - Current  
Massachusetts Institute of Technology, MA, USA

**M.S. in Electrical and Computer Engineering** Sep. 2017 - Mar. 2019  
University of California San Diego, CA, USA

**B.E. in Department of Automation** Aug. 2013 - Jul. 2017  
Tsinghua University, Beijing, China

## PUBLICATIONS

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**Y. Meng**, Z. Qiu, M. Waez and C. Fan, “Case Studies for Computing Density of Reachable States for Safe Autonomous Motion Planning”, in *14th NASA Formal Methods Symposium (NFM)*, 2022 [PDF]

**Y. Meng**, D. Sun, Z. Qiu, M. Waez and C. Fan, “Learning Density Distribution of Reachable States for Autonomous Systems”, in *5th Conference on Robot Learning (CoRL)*, 2021 [PDF]

**Y. Meng**, Z. Qin and C. Fan, “Reactive and Safe Road User Simulations using Neural Barrier Certificates”, in *IEEE/RSJ Int. Conf. on Intelligent Robots and Systems (IROS)*, 2021 [PDF]

**Y. Meng**, R. Panda, C. Lin, P. Sattigeri, L. Karlinsky, K. Saenko, A. Oliva and R. Feris, “AdaFuse: Adaptive Temporal Fusion Network for Efficient Action Recognition,” in *Int. Conf. on Learning Representations (ICLR)*, 2021 [PDF]

**Y. Meng**, C. Lin, R. Panda, P. Sattigeri, L. Karlinsky, K. Saenko, A. Oliva and R. Feris, “AR-Net: Adaptive Frame Resolution for Efficient Action Recognition,” in *European Conf. on Computer Vision (ECCV)*, 2020 (acceptance rate 27.0%) [PDF]

C. Li, **Y. Meng**, S. Chan and Y. Chen, “Learning 3D-aware Egocentric Spatial-Temporal Interaction via Graph Convolutional Networks,” in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, 2020 [PDF]

Q. Feng, **Y. Meng**, M. Shan, and N. Atanasov, “Localization and Mapping using Instance-specific Mesh Models,” in *IEEE/RSJ Int. Conf. on Intelligent Robots and Systems (IROS)*, 2019 [PDF]

**Y. Meng**, Y. Lu, A. Raj, S. Sunarjo, G. Bansal, R. Guo, T. Javidi, and D. Bharadia, “SIGNet: Semantic Instance Aided Unsupervised 3D Geometry Perception,” in *IEEE Conf. on Computer Vision and Pattern Recognition (CVPR)*, 2019 (acceptance rate 25.2%) [PDF]

**Y. Meng**, L. Li, F. Wang, K. Li, and Z. Li, “Analysis of Cooperative Driving Strategies for Nonsignalized Intersections,” *IEEE Transactions on Vehicular Technology (TVT)*, 67 (4), 2900-2911 [PDF]

## AWARDS AND HONORS

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Study Scholarship of Tsinghua University, 2014, 2015

Sports Scholarship of Tsinghua University, 2014, 2015

## TEACHING EXPERIENCE

**Teaching Assistant**, University of California, San Diego, CA, USA Jan. 2019 - Mar. 2019  
Instructor: Behrouz Touri, Electrical and Computer Engineering  
Course: Stochastic Processes in Dynamic Systems I

## RESEARCH EXPERIENCE

**Research Assistant**, Massachusetts Institute of Technology, Cambridge, MA Sep. 2020 - Current  
Advisor: Chuchu Fan, Department of Aeronautics and Astronautics  
– Safe and decentralized multi-agent planning for autonomous driving via control barrier functions  
– Learning-based reachability distribution estimation via solving Liouville PDE  
– Control hybrid systems using differentiable RoA-based planning approach

**Research Intern**, Microsoft Research, WA, USA May. 2022 - Aug. 2022  
Mentor: Sai H. Vemprala, Senior Researcher  
– Learning robot safety concepts from demonstrations.

**AI Resident**, IBM Thomas J. Watson Research Center, NY, USA Sep. 2019 - Aug. 2020  
Mentor: Rogerio S. Feris, Research Manager  
– Efficient video understanding and few-shot learning

**Research Intern**, Honda Research Institute, CA, USA Mar. 2019 - Jun. 2019  
Mentor: Yi-Ting Chen, Research Scientist  
– Proposed a bird’s-eye view representation for driving scene understanding

**Research Assistant**, University of California San Diego, CA, USA Jan. 2018 - Mar. 2019  
Advisor: Nikolay A. Atanasov, Electrical and Computer Engineering  
– Developed semantic perception and tracking pipeline for 3D reconstruction

**Research Assistant**, University of California San Diego, CA, USA Sep. 2018 - Dec. 2018  
Advisor: Dinesh Bharadia, Tara Javidi, Electrical and Computer Engineering  
– Proposed semantic unsupervised learning framework for depth and flow estimation

**Research Assistant**, Tsinghua University, Beijing, China Sep. 2015 - Jun. 2017  
Advisor: Li Li, Department of Automation  
– Designed a traffic simulation platform and analyzed cooperative driving strategies at intersections

## PROFESSIONAL EXPERIENCE

**Software Engineering Intern**, Google Geo, Mountain View, CA, USA Jun. 2019 - Sep. 2019  
– Improved user-photo timestamp correction by using image content-based annotation

**Software Engineering Intern**, Google Ads, New York, NY, USA Jun. 2018 - Sep. 2018  
– Migrated Ads prediction modules from Sibyl to Tensorflow platform

**System Development Intern**, TuSimple, Beijing, China Jul. 2017 - Sep. 2017  
– Implemented Faster-RCNN for cameras on bus and optimized the pipeline by 40%

## TECHNICAL SKILLS

**Programming:** Python, C++, Matlab, Julia, C#

**Tools:** Tensorflow, Pytorch, ROS, Git, Linux, Docker, Kubernetes, L<sup>A</sup>T<sub>E</sub>X

**Languages:** Proficient in English and Chinese